Scheme – I Sample Question Paper

Program Name : Electronics & Telecommunication, Digital Electronics, Industrial

Electronics

Program Code : EJ, DE, IE

Semester : SIXTH

Course Title : Mechatronics

Marks : 70 Time: 3Hrs.

Instructions:

(1) All questions are compulsory.

- (2) Illustrate your answers with neat sketches wherever necessary.
- (3) Figures to the right indicate full marks.
- (4) Assume suitable data if necessary.
- (5) Preferably, write the answers in sequential order.

Q.1 Attempt any FIVE of the following.

(10 Marks)

22643

- a. Define sensor. Enlist any two sensor.
- b. Sketch block diagram of real time mechatronics system.
- c. State any two applications of pneumatic system.
- d. Draw LVDT accelerometer.
- e. State any two applications of Hydraulic System.
- f. State any two applications of Robot.
- g. Define end effector. List any two end effector.

Q.2 Attempt any Three of the following.

(12 Marks)

- a. Sketch the diagram of signal conditioner. Explain it.
- b. State the advantages of CNC machine. Explain G code and M code.
- c. Draw a neat diagram of poppet valve.
- d. State belt. Enlist its type.

Q.3) Attempt any Three of the following.

(12 Marks)

- a. Describe working of load cell with neat sketch.
- b. Illustrate construction features of pneumatic linear actuator.
- c. Explain Hydraulic system with neat sketch.
- d. Describe the working of ABS.

Q.4) Attempt any Three of the following.

- a. Describe working of stroboscope with neat diagram.
- b. Describe the working of electromechanical system with neat diagram.
- c. Explain rack pinon with neat sketch.
- d. Describe degree of freedom w.r.t. robot.
- e. Draw a neat diagram of spool valve.

Q.5) Attempt any Two of the following.

(12 Marks)

- a. State Hall Effect. Enlist its application. Explain any one.
- b. Draw the block diagram of CNC based drilling machine. Explain each block.
- c. Explain basic Pneumatic circuit with neat schematic. Enlist its advantages.

Q.6) Attempt any Two of the following.

- a. Explain working of tachogenerator with neat sketch. Enlist its advantages.
- b. Describe the working of hydraulic rotary actuator with neat sketch. Compare it with linear actuator.
- c. Describe basic concept of automated guided vehicle with neat block diagram.

Scheme – I Sample Test Paper - I

Program Name : Electronics & Telecommunication, Digital Electronics, Industrial

Electronics

Program Code : EJ, DE, IE

Semester : SIXTH

Course Title : Mechatronics

Marks : 20 Time:1 Hour

Instructions:

(1) All questions are compulsory.

- (2) Illustrate your answers with neat sketches wherever necessary.
- (3) Figures to the right indicate full marks.
- (4) Assume suitable data if necessary.
- (5) Preferably, write the answers in sequential order.

Q.1 Attempt any FOUR.

(8 Marks)

22643

- a. List any four sensors.
- b. Give any two advantages of mechatronics system.
- c. Draw LVDT accelerometer.
- d. Draw electromechanical system block diagram.
- e. Describe G code & M code.
- f. Enlist different components of pneumatic system.

Q.2 Attempt any THREE.

- a. Describe mechatronics system with neat sketch.
- b. Describe the working of Hall Effect sensor with neat sketch.
- c. Draw the diagram of mechanical system building block. Explain it in brief.
- d. Describe the working of stroboscope with neat sketch.
- e. Describe the blocks of signal conditioning circuit.

Scheme – I Sample Test Paper - II

Program Name : Electronics & Telecommunication, Digital Electronics, Industrial

Electronics

Program Code : EJ, DE, IE

Semester : SIXTH

Course Title : Mechatronics

Marks : 20 Time:1 Hour

Instructions:

(1) All questions are compulsory.

- (2) Illustrate your answers with neat sketches wherever necessary.
- (3) Figures to the right indicate full marks.
- (4) Assume suitable data if necessary.
- (5) Preferably, write the answers in sequential order.

Q.1 Attempt any FOUR.

(8 Marks)

22643

- a. Draw poppet valve.
- b. Draw spool valve.
- c. Define degree of freedom.
- d. Give application of robot.
- e. Differentiate pneumatic and hydraulic system.
- f. Enlist different types of gear and draw anyone.

Q.2 Attempt any THREE.

- a. Describe with neat sketch the working Spherical robot.
- b. Describe the working of double acting cylinder.
- c. Draw and explain block diagram of pneumatic control system.
- d. Draw and explain block diagram of hydraulic control system
- e. Draw and explain working of pick and place robot.
- f. Draw and explain working of Microcontroller based car park barrier system.